

TENSOR NETWORKS

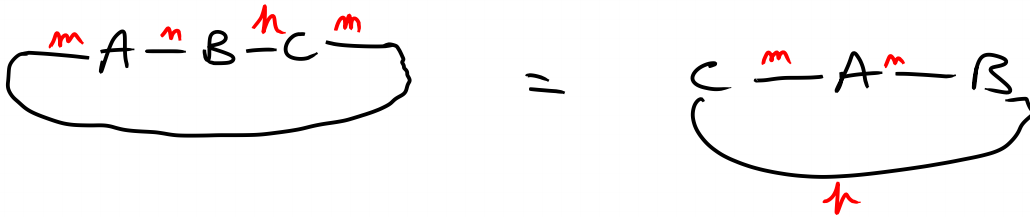
FOR

ANALYSIS OF BENEFITS OF DDTA in RNNs

&

EXPLAINABILITY.

$$\text{Tr}(ABC) = \text{Tr}(CAB) \neq \text{Tr}(CBA)$$



$$A = \begin{pmatrix} | & | & \dots & | \\ a_1 & a_2 & \dots & a_n \\ | & | & \dots & | \end{pmatrix} \in \mathbb{R}^{m \times m}$$

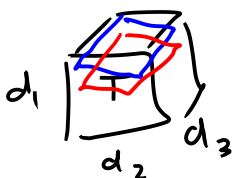


$$\text{vec}(A) = \begin{pmatrix} a_1 \\ \vdots \\ a_m \end{pmatrix} \in \mathbb{R}^{mm}$$



$$T \in \mathbb{R}^{d_1 \times d_2 \times d_3}$$

$$\|T\|_F^2 = T \begin{matrix} d_1 \\ \text{---} \\ d_2 \\ \text{---} \\ d_3 \end{matrix} T = \text{Tr}(\text{vec}(T) \text{vec}(T)^T) = \|\text{vec}(T)\|_F^2$$



$$T_{(i)} \in \mathbb{R}^{d_1 \times d_2 \times d_3}$$

$$\left(\text{---} T \begin{matrix} d \\ \text{---} \\ d \end{matrix} \text{---} M \text{---} \right)_{ij} = \sum_k T_{ik} M_{kj}$$

$$T \in \mathbb{R}^{d \times d \times d}$$



$$\text{vec}(T) = \sum_{i=1}^d T_{:i:i}$$

$$i \text{---} \underset{m}{T} \overset{d}{\text{X}} \overset{d}{T} \text{---} j = \sum_{k=1}^d T_{ik} T_{jk}$$

Outer product $u \in \mathbb{R}^{d_1}, v \in \mathbb{R}^{d_2}$

$$\begin{matrix} u \\ | \\ d_1 \\ i \end{matrix} \begin{matrix} v \\ | \\ d_2 \\ j \end{matrix} = u_i v_j \qquad \begin{matrix} u \\ | \\ v \\ | \end{matrix} = uv^T$$

$$\underbrace{\begin{pmatrix} A & B \\ m & n \end{pmatrix}}_{\mathbb{R}^{m \times n \times n \times q}} :_{ijke} = A_{ij} B_{ke}$$

$A \circ B$

$$\underbrace{\begin{matrix} m & \text{---} & A & \text{---} & n \\ n & \text{---} & B & \text{---} & q \end{matrix}}_{\mathbb{R}^{m \times n \times m \times q}} = \begin{matrix} A \otimes B \\ \uparrow \\ \text{Kronecker Product.} \end{matrix}$$

SEQUENTIAL MODELS

$$h_0, \quad h_t = \phi(h_{t-1}, x_t)$$

$$y_t = \psi(h_t)$$

1st order
Vanilla RNN:

$$h_t = \sigma(Uh_{t-1} + Vx_t)$$

$$y_t = z(Wh_t)$$

2nd order
RNN

$$h_t = \sigma\left(h_{t-1} \overset{m}{\text{---}} \underset{x_t}{\underset{\text{Id}}{\text{A}}} \overset{m}{\text{---}}\right) \in \mathbb{R}^m$$

(linear 2nd order RNN \equiv WFA)

UI

BENEFITS OF DEPTH FOR LONG-TERM MEMORY OF RECURRENT NETWORKS

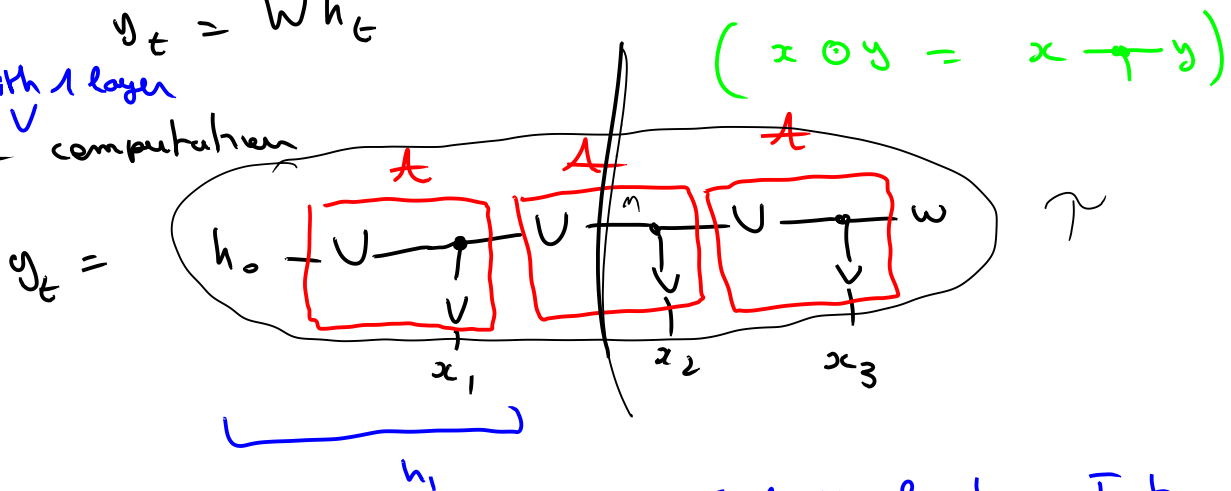
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RAC (recurrent arithmetic circuit)

$$h_t = (Uh_{t-1}) \odot (Vx_t)$$

↑ Hadamard / Component wise product.

$y_t = Wh_t$
with 1 layer
RAC computation



(Multiplicative Interaction RNN)

RAC with L layers:

$$h_t^{(1)} = (U^{(1)} h_{t-1}^{(1)}) \odot (V^{(1)} x_t)$$

$$h_t^{(2)} = (U^{(2)} h_{t-1}^{(2)}) \odot (V^{(2)} h_t^{(1)})$$

$$\vdots$$

$$h_t^{(L)} = (U^{(L)} h_{t-1}^{(L)}) \odot (V^{(L)} h_t^{(L-1)})$$

$$y_t = W h_t^{(L)}$$

Def: Separation rank.

Let $f: \mathcal{X}^T \rightarrow \mathbb{R}$. For any $t=1 \dots T$

\uparrow
 (x_1, x_2, \dots, x_T)
 \uparrow
 $\in \mathcal{X}$

$$\text{sep}_t(f) = \min \{ R \in \mathbb{N} \mid \exists g_1, \dots, g_R, h_1, \dots, h_R$$

$$f(x_1, \dots, x_T) = \sum_{n=1}^R g_n(x_1, \dots, x_t) h_n(x_{t+1}, \dots, x_T)$$

$$\forall x_1, x_2, \dots, x_T \in \mathcal{X} \}$$

Intuition: If $\text{sep}_t(f) = 1$, then

$$f(x_1, \dots, x_T) = g(x_1, \dots, x_t) h(x_{t+1}, \dots, x_T)$$

$$f: x_1, x_2, \dots, x_{T/2} \mid x_{T/2+1}, \dots, x_T$$

$\text{sep}_{T/2}(f)$

Lemma 1: If $\mathcal{X} = \mathbb{R}^d$ and

$$f: x_1, x_2, \dots, x_T \mapsto A \in \mathbb{R}$$

$\downarrow \downarrow \downarrow \dots \downarrow$
 $x_1 \ x_2 \ x_3 \ \dots \ x_T$

$\langle A, x_1 \otimes x_2 \otimes \dots \otimes x_T \rangle$

where $A \in \mathbb{R}^{\underbrace{d \times \dots \times d}_{T \text{ times}}}$

$$\text{sep}_t(f) = \text{rank}(\llbracket A \rrbracket_{(1, \dots, t), (t+1, \dots, T)})$$

Def: Let $f: \mathcal{X}^T \rightarrow \mathbb{R}$ be an arbitrary function

The grid tensor of f w.r.t. the template vectors $x_1, x_2, \dots, x_k \in \mathcal{X}$

is the tensor $A(f) \in \mathbb{R}^{\underbrace{k \times k \times \dots \times k}_{T \text{ times}}}$ is defined by

$$A(f)_{i_1, i_2, \dots, i_T} = f(x_{i_1}, x_{i_2}, \dots, x_{i_T})$$

↳ ex $T=2$, template vectors x_1, x_2, x_3

$$A(f) \in \mathbb{R}^{3 \times 3}$$

$$A(f) = \begin{bmatrix} f(x_1, x_1) & f(x_1, x_2) & f(x_1, x_3) \\ f(x_2, x_1) & f(x_2, x_2) & f(x_2, x_3) \\ f(x_3, x_1) & f(x_3, x_2) & f(x_3, x_3) \end{bmatrix}$$

Lemma 2: Let $f: \mathcal{X}^T \rightarrow \mathbb{R}$. For any template vectors $x_1, x_2, \dots, x_n \in \mathcal{X}$ the grid tensor $A(f)$ is st.

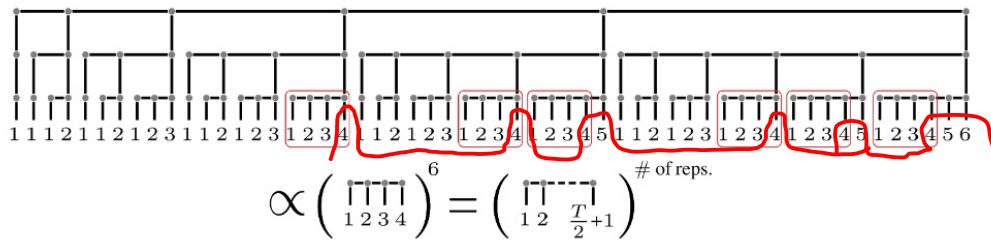
$$\text{sep}_t(f) \geq \text{rank} \left(\llbracket A(f) \rrbracket_{(1, \dots, t) (t+1, \dots, T)} \right)$$

Thm Consider a RAC with n neurons and L layers. $\mathcal{X} = \mathbb{R}^d$
 Assume $n \leq d$

Shallow RAC ($L=1$): $\text{sep}_{T/2}(f) = n$ (with P 1)

DEEP RAC ($L=2$): $\text{sep}_{T/2}(f) \gtrsim \frac{4^n}{4\sqrt{\pi(n-1)}}$
 exp. dependency on n

$L=3$

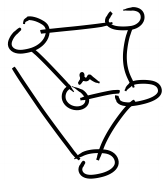


ENTANGLEMENT ENTROPY.



Explainable Natural Language Processing with Matrix Product States

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$$f_u: x_{n_1}, \dots, x_{n_{|U|}} \mapsto \mathbb{R}$$

$$\text{sep}_{\{u\}, V \setminus \{u\}}(f_u)$$

$$\text{sep}_{\{1\text{-Hop}(u)\}, V \setminus \{1\text{-Hop}(u)\}}(f_u)$$

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Wacom Tablet.